

Online Course Materials :

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Unit/Chapter /Module : unit -3

Topic / Title : Problems and solutions on vector operators |

8(b) differentiate w.r.t t

$$r^2 \vec{r} + (\vec{a} \cdot \vec{r}) \vec{b} \quad \text{where}$$

$|\vec{r}| = r$ & \vec{a}, \vec{b} are constant vectors.

Solution:

$$\frac{d}{dt} \left\{ r^2 \vec{r} + (\vec{a} \cdot \vec{r}) \vec{b} \right\}$$

$$= \frac{d}{dt} (r^2) \vec{r} + r^2 \frac{d\vec{r}}{dt} +$$

$$\left\{ \frac{d}{dt} (\vec{a} \cdot \vec{r}) \right\} \vec{b} + (\vec{a} \cdot \vec{r}) \frac{d\vec{b}}{dt}$$

$$= 2r \frac{dr}{dt} \vec{r} + r^2 \frac{d\vec{r}}{dt} + \left\{ \left(\frac{d\vec{a}}{dt} \cdot \vec{r} \right) + (\vec{a} \cdot \frac{d\vec{r}}{dt}) \right\} \vec{b} + \vec{0} \quad (\because \frac{d\vec{b}}{dt} = 0)$$

$$= 2r \frac{dr}{dt} \vec{r} + r^2 \frac{d\vec{r}}{dt} + \left(\vec{a} \cdot \frac{d\vec{r}}{dt} \right) \vec{b}$$

$$\left(\because \frac{d\vec{a}}{dt} = \vec{0} \text{ as } \vec{a} \text{ is a constant vector} \right)$$

\vec{a} is a constant vector.

(10) Show that $\vec{A} = (6xy + z^3)\hat{i} + (3x^2 - z)\hat{j} + (3xz^2 - y)\hat{k}$ is irrotational. Find ϕ such that $\vec{A} = \nabla\phi$ and $\phi(1,1,1) = 3$

Solution: curl $\vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 6xy + z^3 & 3x^2 - z & 3xz^2 - y \end{vmatrix}$

$$= \begin{pmatrix} -1+1 \\ 6x - 6x \\ 3z^2 - 3z^2 \end{pmatrix} \hat{i} + \begin{pmatrix} 3z^2 - 3z^2 \end{pmatrix} \hat{j} + \begin{pmatrix} 0 \end{pmatrix} \hat{k}$$

$$= \vec{0}$$

$\therefore \vec{A}$ is an irrotational vector.

2nd part : Let $\vec{A} = \vec{\nabla} \phi$

$$= \frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k}$$

$$\therefore \frac{\partial \phi}{\partial x} = 6xy + z^3$$

$$\frac{\partial \phi}{\partial y} = 3x^2 - z$$

$$\frac{\partial \phi}{\partial z} = 3xz^2 - y$$

We know that

$$\begin{aligned} d\phi &= \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz \\ &= (6xy + z^3) dx + (3x^2 - z) dy \\ &\quad + (3xz^2 - y) dz \end{aligned}$$

$$= 6xy dx + 3x^2 dy + (z^3 dx + 3xz^2 dz) - (z dy + y dz)$$

$$= d(3x^2 y) + d(z^3 x) - d(yz)$$

$$= d(3x^2 y + z^3 x - yz)$$

Integrating,

$$\phi = 3x^2 y + z^3 x - yz + c \quad \text{where } c \text{ is}$$

an arbitrary constant.

Since $\phi(1, 1, 1) = 3$, so we get

$$3 + 1 - 1 + c = 3$$

$$\Rightarrow c = 0$$

$$\therefore \phi = 3x^2 y + z^3 x - yz$$

Alternatively: Since $\frac{\partial \phi}{\partial x} = 6xy + z^3$, so

$$\phi = 3x^2 y + z^3 x + \psi_1(y, z) \quad \dots (1)$$

Again as $\frac{\partial \phi}{\partial y} = 3x^2 - z$, so we get

$$\phi = 3x^2 y - yz + \psi_2(x, z) \dots (2)$$

Again $\frac{\partial \phi}{\partial z} = 3xz^2 - y$, so we get

$$\phi = xz^3 - yz + \psi_3(x, y) \dots (3)$$

From (1), (2) & (3), we get that

$$\phi = 3x^2 y + z^3 x - yz + C \quad \text{where}$$

C is an arbitrary constant.

Since $\phi(1, 1, 1) = 3$, so $C = 0$

$$\therefore \phi = 3x^2 y + z^3 x - yz.$$

(ii) Prove that $\nabla \times (\nabla \times \vec{F}) = \nabla(\nabla \cdot \vec{F}) - \nabla^2 \vec{F}$

Solution: Let $\vec{F} = F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k}$

Then $\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$

$$= \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \hat{i} + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \hat{j}$$

$$+ \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \hat{k}$$

$$\therefore \nabla \times (\nabla \times \vec{F}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} & \frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} & \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \end{vmatrix}$$

$$= \sum \left(\frac{\partial^2 F_2}{\partial y \partial x} - \frac{\partial^2 F_1}{\partial y^2} - \frac{\partial^2 F_1}{\partial z^2} + \frac{\partial^2 F_3}{\partial x \partial z} \right) \hat{i} \dots (1)$$

$$\nabla (\nabla \cdot \vec{F}) = \nabla^2 \vec{F}$$

$$= \nabla \left(\frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \right) - \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right)$$

$$= \sum \frac{\partial}{\partial x} \left(\frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \right) \hat{i} - \sum \left(\frac{\partial^2 F_1}{\partial x^2} + \frac{\partial^2 F_1}{\partial y^2} + \frac{\partial^2 F_1}{\partial z^2} \right) \hat{i}$$

$(F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k})$

$$= \sum \left(\frac{\partial^2 F_1}{\partial x^2} + \frac{\partial^2 F_2}{\partial x \partial y} + \frac{\partial^2 F_3}{\partial x \partial z} - \frac{\partial^2 F_1}{\partial x^2} \right) \hat{i}$$

$$= \sum \left(\frac{\partial^2 F_2}{\partial x \partial y} + \frac{\partial^2 F_3}{\partial x \partial z} - \frac{\partial^2 F_1}{\partial y^2} - \frac{\partial^2 F_1}{\partial z^2} \right) \hat{i} \dots (2)$$

from (1) & (2) we get

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{F}) = \vec{\nabla} (\vec{\nabla} \cdot \vec{F}) - \nabla^2 \vec{F} \text{ (boxed)}$$

10. If $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$, $r = |\vec{r}|$ and \vec{a} is a constant vector, then show that

a) $\text{Curl} (\vec{a} \times \vec{r}) = 2\vec{a}$

b) $\text{grad } r^n = nr^{n-2} \vec{r}$

c) $\text{curl} \left\{ r^n (\vec{a} \times \vec{r}) \right\} = (n+2)r^{n-1} \vec{a} - nr^{n-2} (\vec{r} \cdot \vec{a}) \vec{r}$

Solution: Let $\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$ where a_1, a_2, a_3

are scalars.

Then $\vec{a} \times \vec{r} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ x & y & z \end{vmatrix}$

$= (a_2z - a_3y)\hat{i} + (a_3x - a_1z)\hat{j} + (a_1y - a_2x)\hat{k}$

$\therefore \text{curl} \left\{ r^n (\vec{a} \times \vec{r}) \right\} = \vec{\nabla} \times \left\{ r^n (\vec{a} \times \vec{r}) \right\}$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ r^n (a_2 z - a_3 y) & r^n (a_3 x - a_1 z) & r^n (a_1 y - a_2 x) \end{vmatrix}$$

$$= \sum \left\{ \frac{\partial}{\partial y} \left\{ r^n (a_1 y - a_2 x) \right\} - \frac{\partial}{\partial z} \left(r^n (a_3 x - a_1 z) \right) \right\}$$

$$= \sum \left\{ \left(r^n a_1 + n r^{n-1} \frac{\partial r}{\partial y} (a_1 y - a_2 x) \right) - \left(r^n (-a_1) + (a_3 x - a_1 z) n r^{n-1} \frac{\partial r}{\partial z} \right) \right\}$$

$$= \sum \left\{ r^n a_1 + n r^{n-1} \frac{y}{r} (a_1 y - a_2 x) + a_1 r^n - n r^{n-1} \frac{z}{r} (a_3 x - a_1 z) \right\}$$

$$\left[\begin{array}{l} \because r^2 = x^2 + y^2 + z^2 \\ 2r \frac{\partial r}{\partial y} = 2y \end{array} \right]$$

$$= \sum \left[\left(2 r^n a_1 + n r^{n-2} \left(y (a_1 y - a_2 x) - z (a_3 x - a_1 z) \right) \right) \hat{i} \right]$$

$$= 2 r^n \sum a_i \hat{i} + n r^{n-2} \left[\begin{array}{l} y (a_1 y - a_2 x) - z (a_3 x - a_1 z) \\ + (z (a_2 z - a_3 y) - x (a_1 y - a_2 x)) \\ + (x (a_3 x - a_1 z) - y (a_2 z - a_3 y)) \end{array} \right]$$

$$= 2r^n \vec{a} + nr^{n-2} \left\{ \begin{aligned} & a_1 y^2 \hat{i} + a_1 z^2 \\ & y^2 (a_1 \hat{i} + a_3 \hat{k}) + \\ & x^2 (a_2 \hat{j} + a_3 \hat{k}) + \\ & z^2 (a_1 \hat{i} + a_2 \hat{j}) \\ & - a_2 xy \hat{i} - a_3 xz \hat{i} \\ & - a_3 zy \hat{j} - a_1 xy \hat{j} \\ & - a_1 xz \hat{k} - a_2 yz \hat{k} \end{aligned} \right\}$$

$$= 2r^n \vec{a} + nr^{n-2} \left\{ \begin{aligned} & y^2 \vec{a} - y^2 a_2 \hat{j} + x^2 \vec{a} - x^2 a_1 \hat{i} \\ & + z^2 \vec{a} - z^2 a_3 \hat{k} - a_2 xy \hat{i} - a_3 xz \hat{i} \\ & - a_3 zy \hat{j} - a_1 xy \hat{j} - \\ & a_1 xz \hat{k} - a_2 yz \hat{k} \end{aligned} \right\}$$

$$= 2r^n \vec{a} + nr^{n-2} \left\{ \begin{aligned} & (x^2 + y^2 + z^2) \vec{a} - ya_2 (y \hat{j} + x \hat{i} + z \hat{k}) \\ & - xa_1 (x \hat{i} + y \hat{j} + z \hat{k}) \\ & - za_3 (z \hat{k} + y \hat{j} + x \hat{i}) \end{aligned} \right\}$$

$$= 2r^n \vec{a} + nr^{n-2} \left\{ r^2 \vec{a} - (xa_1 + ya_2 + za_3) \vec{r} \right\}$$

$$= 2r^n \vec{a} + nr^n \vec{a} - nr^{n-2} (\vec{r} \cdot \vec{a}) \vec{r} = (2+n)r^n \vec{a} - nr^{n-2} (\vec{r} \cdot \vec{a}) \vec{r}$$

If \hat{a} is a unit vector in the direction of \vec{b} ,

$$\text{show that } \hat{a} \times \frac{d\hat{a}}{dt} = \frac{1}{b^2} \left(\vec{b} \times \frac{d\vec{b}}{dt} \right)$$

Solution: Since \hat{a} is a unit vector in the direction of \vec{b} , so we get

$$\hat{a} = \frac{\vec{b}}{b} \quad \text{where } b = |\vec{b}|$$

$$\text{Now } \hat{a} \times \frac{d\hat{a}}{dt} = \frac{\vec{b}}{b} \times \frac{d}{dt} \left(\frac{\vec{b}}{b} \right)$$

$$= \frac{\vec{b}}{b} \times \left(\frac{1}{b} \frac{d\vec{b}}{dt} + \left(-\frac{1}{b^2} \frac{db}{dt} \vec{b} \right) \right)$$

$$= \frac{1}{b^2} \left(\vec{b} \times \frac{d\vec{b}}{dt} \right) - \frac{1}{b^3} \frac{db}{dt} (\vec{b} \times \vec{b})$$

$$= \frac{1}{b^2} \left(\vec{b} \times \frac{d\vec{b}}{dt} \right)$$

11(a) Find the directional derivative of the function $f(x, y, z) = x^2 - y^2 + z^2$ at the pt $P(1, 2, -3)$ in the direction of the vector \vec{PQ} where Q is the pt $(3, 1, 2)$ [2]

Solution: Let \hat{n} be the unit vector in the direction of \vec{PQ}

$$\hat{n} = \frac{2\hat{i} - \hat{j} + 5\hat{k}}{\sqrt{4+1+25}}$$

$$\begin{aligned} \therefore \text{The directional derivative of } f(x, y, z) \text{ at } (1, 2, -3) &= \left. (\nabla f) \cdot \hat{n} \right|_{(1, 2, -3)} \\ &= (2x\hat{i} - 2y\hat{j} + 2z\hat{k}) \cdot \left(\frac{2\hat{i} - \hat{j} + 5\hat{k}}{\sqrt{30}} \right) \Big|_{(1, 2, -3)} \end{aligned}$$

$$= \frac{2}{\sqrt{30}} (2x + y + 5z) \Big|_{(1, 2, -3)}$$

$$= \frac{2}{\sqrt{30}} (2 + 2 - 15)$$

$$= -\frac{22}{\sqrt{30}}$$

10. Let $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$, $r = |\vec{r}|$ and $f(r)$ be a scalar function possessing first and 2nd order derivatives. Prove that

$$\nabla^2 f(r) = \frac{d^2 f}{dr^2} + \frac{2}{r} \frac{df}{dr}$$

Solution: Since $r = |\vec{r}|$, so $r^2 = x^2 + y^2 + z^2$

$$\text{Now } \frac{\partial}{\partial x} (f(r)) = \frac{df}{dr} \frac{\partial r}{\partial x}$$

$$= \frac{df}{dr} \frac{x}{r} \quad \left(\because r^2 = x^2 + y^2 + z^2, \text{ so } 2r \frac{\partial r}{\partial x} = 2x \right)$$

$$\text{Similarly } \frac{\partial f}{\partial y} = \frac{df}{dr} \frac{y}{r}, \quad \frac{\partial f}{\partial z} = \frac{df}{dr} \frac{z}{r}$$

$$\text{Now, } \nabla^2 f(r) = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

$$= \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial f}{\partial z} \right)$$

$$= \frac{\partial}{\partial x} \left(\frac{df}{dr} \frac{x}{r} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dr} \frac{y}{r} \right) + \frac{\partial}{\partial z} \left(\frac{df}{dr} \frac{z}{r} \right)$$

$$= \frac{df}{dr} \frac{\partial}{\partial x} \left(\frac{x}{r} \right) + \frac{\partial}{\partial x} \left(\frac{df}{dr} \right) \frac{x}{r} + \dots$$

$$= \frac{df}{dr} \left(\frac{r \cdot 1 - x \frac{\partial r}{\partial x}}{r^2} \right) + \frac{\partial}{\partial r} \left(\frac{df}{dr} \right) \frac{\partial r}{\partial x} \frac{x}{r} + \dots$$

$$= \frac{df}{dr} \frac{r - \frac{x^2}{r}}{r^2} + \frac{d^2 f}{dr^2} \frac{x^2}{r^2} + \frac{df}{dr} \frac{r - \frac{y^2}{r}}{r^2}$$

$$+ \frac{d^2 f}{dr^2} \left(\frac{y}{r} \right)^2 + \frac{df}{dr} \frac{r - \frac{z^2}{r}}{r^2} + \frac{d^2 f}{dr^2} \left(\frac{z}{r} \right)^2$$

$$= \frac{d^2 f}{dr^2} \left(\frac{x^2 + y^2 + z^2}{r^2} \right) + \frac{df}{dr} \left(\frac{3r^2 - (x^2 + y^2 + z^2)}{r^3} \right)$$

$$= \frac{d^2 f}{dr^2} + \frac{2}{r} \frac{df}{dr} \quad (\text{Proved}).$$

11 (a) Show that the vector field ^{vectors} determined by

$r^n \vec{p}$ where $\vec{p} = x\hat{i} + y\hat{j} + z\hat{k}$ and $r = |\vec{p}|$ is solenoidal for $n = -3$

Solution: Since $n = -3$, so $r^n \vec{p} = \frac{\vec{p}}{r^3}$

Now $\text{div} \left(\frac{\vec{p}}{r^3} \right)$

$$= \text{div} \left(\frac{x}{r^3} \hat{i} + \frac{y}{r^3} \hat{j} + \frac{z}{r^3} \hat{k} \right)$$

$$= \frac{\partial}{\partial x} \left(\frac{x}{r^3} \right) + \frac{\partial}{\partial y} \left(\frac{y}{r^3} \right) + \frac{\partial}{\partial z} \left(\frac{z}{r^3} \right)$$

$$= \sum \frac{r^3 \cdot 1 - x \cdot 3r^2 \frac{\partial r}{\partial x}}{r^6}$$

$$= \sum \frac{r^3 - 3r^2 \frac{x^2}{r}}{r^6}$$

$$\left(\begin{array}{l} \because r^2 = x^2 + y^2 + z^2 \\ \therefore 2r \frac{\partial r}{\partial x} = 2x \end{array} \right)$$

$$= \sum \frac{r^3 - 3rx^2}{r^6}$$

$$= \frac{3r^3 - 3r(x^2 + y^2 + z^2)}{r^6}$$

$$= \frac{3r^3 - 3r^3}{r^6} = 0$$

$\therefore \frac{\vec{r}}{r^3}$ is a solenoidal vector

(b) For what value of the constant a , will the vector field $\vec{A} = (axy - z^3)\hat{i} + (a-2)x^2\hat{j} + (1-a)xz^2\hat{k}$ be always irrotational?

Solution: Since \vec{A} is irrotational, so $\text{curl } \vec{A} = \vec{0}$

$$\text{Then } \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ axy - z^3 & (a-2)x^2 & (1-a)xz^2 \end{vmatrix} = \vec{0}$$

$$\Rightarrow \left(-3z^2 - (1-a)z^2 \right) \hat{j} + \left(2x(a-2) - ax \right) \hat{k} = \vec{0}$$

$$\Rightarrow -3 - (1-a) = 0 \dots \Rightarrow a - 4 = 0$$

$$ax - 4 = 0 \Rightarrow a = 4 \text{ (Ans).}$$

9. Define directional derivatives of a scalar pt function ϕ at a pt along any semi line through that pt. Find the maximum value of the directional derivatives of $\phi = xy^2 + 2yz - 3x^3z^2$ at the pt $(1, -1, 1)$. Find also the directional in which it occurs. [2+2+1].

Solution:



We consider a pt P and a semi line \vec{PA} through P . Then the directional derivative of ϕ at P along \vec{PA} is defined by

$$(\nabla\phi)_P \cdot \frac{\vec{PA}}{|\vec{PA}|} \quad \text{where } \nabla\phi = \frac{\partial\phi}{\partial x} \hat{i} + \frac{\partial\phi}{\partial y} \hat{j} + \frac{\partial\phi}{\partial z} \hat{k}.$$

2nd part : $\vec{\nabla} \phi = (y^2 - 9x^2z^2) \hat{i} + (2xy + 2z) \hat{j} + (2y - 6x^3z) \hat{k}$

$$\therefore \vec{\nabla} \phi \Big|_{(1, -1, 1)} = -8 \hat{i} - 8 \hat{k}$$

\therefore Maximum directional derivative of ϕ

$$= |\vec{\nabla} \phi| = \sqrt{64 + 64} = 8\sqrt{2}$$

It occurs in the direction of $(\vec{\nabla} \phi)_{(1, -1, 1)}$

ie in the direction of $-8(\hat{i} + \hat{k})$